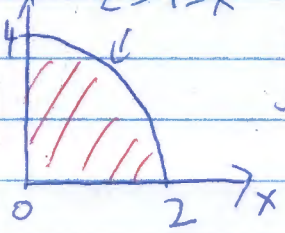


Solution for HW6

P.1

Ex 15.5: 44) $\int_0^2 \int_0^{4-x^2} \int_0^x \frac{\sin 2z}{4-z} dy dz dx = \int_0^2 \int_0^{4-x^2} \frac{\sin 2z}{4-z} x dz dx =$



$\int_0^4 \int_0^{\sqrt{4-z}} \frac{\sin 2z}{4-z} x dx dz = \frac{1}{2} \int_0^4 \sin 2z dz = \frac{1-\cos 8}{4}$ (or $\frac{\sin^2 4}{2}$)

Ex 15.6: 28) $I_L = \int_{-2}^2 \int_{-2}^4 \int_{-1}^{\frac{z-y}{2}} [(x-4)^2 + y^2] dz dy dx$

$= \frac{1}{2} \int_{-2}^2 \int_{-2}^4 (x^2 - 8x + 16 - y^2)(4-y) dy dx$

$= \frac{1}{2} \int_{-2}^2 \int_{-2}^4 (4x^2 - 32x + 64 - 4y^2 - xy + 8xy - 16y - y^3) dy dx$

$= \int_{-2}^2 (9x^2 - 72x + 162) dx$

$= 696$

30) a) $M = \int_0^2 \int_0^{\sqrt{x}} \int_0^{4-x^2} kxy dz dy dx = \int_0^2 \int_0^{\sqrt{x}} kxy(4-x^2) dy dx$

$= \frac{1}{2} \int_0^2 kx^2(4-x^2) dx = \frac{32k}{15}$

b) $M_{yz} = \int_0^2 \int_0^{\sqrt{x}} \int_0^{4-x^2} kxy^2 dz dy dx = \int_0^2 \int_0^{\sqrt{x}} kxy^2(4-x^2) dy dx$

$= \frac{1}{2} \int_0^2 kx^3(4-x^2) dx = \frac{8k}{3} \Rightarrow \bar{x} = \frac{M_{yz}}{M} = \frac{5}{4}$

$M_{xz} = \int_0^2 \int_0^{\sqrt{x}} \int_0^{4-x^2} kxy^2 dz dy dx = \int_0^2 \int_0^{\sqrt{x}} kxy^2(4-x^2) dy dx$

$= \frac{1}{3} \int_0^2 kx^{\frac{5}{2}}(4-x^2) dx = \frac{256\sqrt{2}}{231} k \Rightarrow \bar{y} = \frac{M_{xz}}{M} = \frac{40\sqrt{2}}{77}$

$M_{xy} = \int_0^2 \int_0^{\sqrt{x}} \int_0^{4-x^2} kxyz dz dy dx = \int_0^2 \int_0^{\sqrt{x}} kxy \frac{(4-x^2)^2}{2} dy dx$

$= \frac{1}{4} \int_0^2 kx^2(4-x^2) dx = \frac{256}{105} k \Rightarrow \bar{z} = \frac{M_{xy}}{M} = \frac{8}{7}$

$$36) \text{ By Parallel Axis Theorem, } I_L = I_{c.m.} + mh^2 = \frac{2}{5} ma^2 + ma^2 = \frac{7}{5} ma^2$$

$$\text{Ex 15.7: } 12) \text{ a) } \int_0^{2\pi} \int_0^1 \int_r^{2r^2} r \, dz \, dr \, d\theta //$$

$$\text{b) } \int_0^{2\pi} \int_0^1 \int_0^z r \, dr \, dz \, d\theta + \int_0^{2\pi} \int_1^2 \int_0^{\sqrt{2z}} r \, dr \, dz \, d\theta //$$

$$\text{c) } \int_0^1 \int_r^{2r^2} \int_0^{2\pi} r \, d\theta \, dz \, dr //$$

$$14) \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \int_0^1 \int_0^{\cos\theta} 3r \, dz \, dr \, d\theta = \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \int_0^1 r^4 \cos\theta \, dr \, d\theta$$

$$= \frac{1}{5} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos\theta \, d\theta = \frac{2}{5} //$$

$$38) \text{ a) } V = \int_0^{2\pi} \int_{\frac{\pi}{3}}^{\frac{\pi}{2}} \int_0^2 \rho^2 \sin\phi \, d\rho \, d\phi \, d\theta = 2\pi \int_{\frac{\pi}{3}}^{\frac{\pi}{2}} \int_0^2 \rho^2 \sin\phi \, d\rho \, d\phi$$

$$= (2\pi) \left(\frac{8}{3}\right) \int_{\frac{\pi}{3}}^{\frac{\pi}{2}} \sin\phi \, d\phi = \frac{8\pi}{3} //$$

$$40) \text{ a) } \int_0^{\frac{\pi}{2}} \int_{\frac{\pi}{2}}^{\frac{3}{2}} \int_r^{\sqrt{4r^2}} r \, dz \, dr \, d\theta //$$

$$\text{b) } \int_0^{\frac{\pi}{2}} \int_{\frac{\pi}{4}}^{\frac{3}{4}} \int_0^3 \rho^2 \sin\phi \, d\rho \, d\phi \, d\theta //$$

$$\text{c) } \int_0^{\frac{\pi}{2}} \int_{\frac{\pi}{4}}^{\frac{3}{4}} \int_0^3 \rho^2 \sin\phi \, d\rho \, d\phi \, d\theta = \frac{\pi}{2} \int_0^{\frac{\pi}{4}} \int_0^3 \rho^2 \sin\phi \, d\rho \, d\phi$$

$$= \left(\frac{\pi}{2}\right) (9) \int_0^{\frac{\pi}{4}} \sin\phi \, d\phi = \frac{9\pi (2-\sqrt{2})}{4} //$$

$$62) \begin{cases} x^2 + y^2 + z^2 = 2 \\ z = x^2 + y^2 \end{cases} \Rightarrow z^2 + z - 2 = 0 \Rightarrow z = 1 \text{ or } -2 \text{ (rejected)}$$

$$V = \int_0^{2\pi} \int_0^1 \int_r^{\sqrt{2-r^2}} r dz dr d\theta = 2\pi \int_0^1 \int_r^{\sqrt{2-r^2}} r dr d\theta$$

$$= 2\pi \int_0^1 r(\sqrt{2-r^2} - r) dr = \frac{\pi(8\sqrt{2}-7)}{6} \quad \text{,,}$$

80) Let a and h be the base radius and height of the cone respectively.

Put the cone in \mathbb{R}^3 s.t. the axis of symmetry is the z -axis and the vertex of the cone is $(0,0,0)$.

Then $M = \frac{\pi a^2 h}{3}$ and

$$M_{xy} = \int_0^{2\pi} \int_0^a \int_{\frac{h}{a}r}^h zr dz dr d\theta = 2\pi \int_0^a \int_{\frac{h}{a}r}^h zr dz dr$$

$$= (2\pi) \left(\frac{1}{2}\right) \int_0^a \left(h^2 - \frac{h^2}{a^2}r^2\right) r dr = \frac{h^2 a^2 \pi}{4}$$

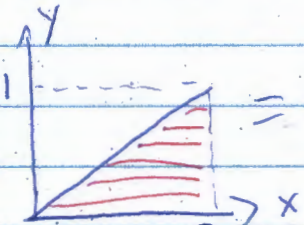
$$\therefore \bar{z} = \frac{M_{xy}}{M} = \frac{3}{4}h.$$

By symmetry, $\bar{x} = 0 = \bar{y}$.

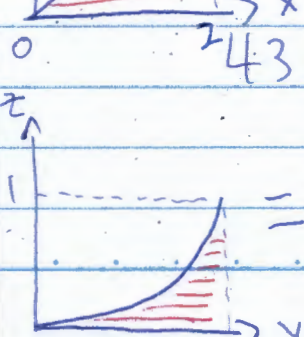
\Rightarrow The centroid is $\frac{1}{4}$ of the way from the base to the vertex.

Practice Problems:

Ex 15.5: 41) $\int_0^4 \int_0^1 \int_{2y}^2 \frac{4 \cos(x^2)}{2\sqrt{z}} dx dy dz = \int_0^1 \int_0^2 \int_0^{\frac{x}{2}} \frac{4 \cos(x^2)}{2\sqrt{z}} dy dx dz$



$$= \int_0^4 \int_0^2 \frac{\cos(x^2)}{z} x dx dz = \frac{\sin 4}{2} \int_0^4 \frac{1}{z^{\frac{1}{2}}} dz = 2 \sin 4 \quad \text{,,}$$



43) $\int_0^1 \int_{z^{\frac{1}{3}}}^1 \int_0^{\ln z} \frac{\pi e^{2x} \sin(\pi y^2)}{y^2} dx dy dz = 4 \int_0^1 \int_{z^{\frac{1}{3}}}^1 \frac{\pi \sin(\pi y^2)}{y^2} dy dz$

$$= 4 \int_0^1 \int_0^{y^3} \frac{\pi \sin(\pi y^2)}{y^2} dz dy = 4 \int_0^1 \sin(\pi y^2) (\pi y) dy = 4 \quad \text{,,}$$

Ex 15.6: 35) a) WLOG, assume that the centre of mass is placed in yz -plane. Then $\bar{x} = 0$ and $M_{yz} = \bar{x}M = 0$.

$$\begin{aligned}
 b) I_z &= \iiint_D |r-h|^2 dm = \iiint_D (x^2 - 2xh + h^2 + y^2) dm \\
 &= \iiint_D (x^2 + y^2) dm - 2h \iiint_D x dm + h^2 \iiint_D dm \\
 &= I_{c.m.} - 2h M_{yz} + h^2 m \\
 &= I_{c.m.} + mh^2
 \end{aligned}$$

Ex 15.7: 35) $V = \int_0^{2\pi} \int_0^\pi \int_0^{h \cos \phi} \rho^2 \sin \phi d\rho d\phi d\theta = 2\pi \int_0^\pi \int_0^{h \cos \phi} \rho^2 \sin \phi d\rho d\phi$

$$\begin{aligned}
 &= \frac{2\pi}{3} \int_0^\pi (h \cos \phi)^3 \sin \phi d\phi = -\frac{2\pi}{3} \int_0^\pi (h \cos \phi)^3 d(h \cos \phi) \\
 &= -\frac{2\pi}{3} \left[\frac{1}{4} (h \cos \phi)^4 \right]_0^\pi = \frac{8\pi}{3}
 \end{aligned}$$

37) $V = \int_0^{2\pi} \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \int_0^{2 \cos \phi} \rho^2 \sin \phi d\rho d\phi d\theta = 2\pi \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \int_0^{2 \cos \phi} \rho^2 \sin \phi d\rho d\phi$

$$\begin{aligned}
 &= 2\pi \left(\frac{8}{3} \right) \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \cos^3 \phi \sin \phi d\phi = \frac{16\pi}{3} \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \cos^3 \phi d \cos \phi \\
 &= \frac{\pi}{3}
 \end{aligned}$$

81) Let $\delta(r) = kr + C$ for some $k \neq 0, C \in \mathbb{R}$.

As $\delta(R) = 0$, we have $C = -kR$.

$$\therefore \delta(r) = k(r - R)$$

Note that $M = \int_0^{2\pi} \int_0^\pi \int_0^R \rho^2 k(\rho - R) \sin \phi d\rho d\phi d\theta$

$$\begin{aligned}
 &= 2\pi \int_0^\pi \int_0^R \rho^2 k(\rho - R) \sin \phi d\rho d\phi = 2\pi \int_0^\pi \left(\frac{kR^4}{4} - \frac{kR^4}{3} \right) \sin \phi d\phi
 \end{aligned}$$

$$= (2\pi) \left(\frac{-kR^4}{12} \right) (z) = \frac{-k\pi R^4}{3}$$

$$\therefore k = \frac{-3M}{\pi R^4} \quad \text{and} \quad \delta(b) = -kR = \frac{3M}{\pi R^3} //$$

85) The equation $r=f(z)$ implies that $(f(z), z, \theta)$ lies on the surface $\forall \theta$. So the surface is symmetric along z -axis.

86) The equation $\rho=f(\phi)$ implies that $(f(\phi), \phi, \theta)$ lies on the surface $\forall \theta$. So the surface is symmetric along z -axis.